

Fluid Simulation with Smoothed Particle Hydrodynamics

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Intro to SPH

- **Navier-Stokes Equations**
 - Movement
 - Incompressibility
- **Components of fluid motion**
 - Density
 - Pressure
 - Viscosity

*u: velocity, p: pressure, ρ : density,
 ν : coefficient of viscosity*

$$\rho \dot{\mathbf{u}} = -\rho(\nabla \cdot \mathbf{u})\mathbf{u} - \nabla p + \nu \nabla^2 \mathbf{u} + \mathbf{F}$$

$$\nabla \cdot \mathbf{u} = 0$$

[1] Pelfrey (2009)

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$$\rho \dot{\mathbf{u}} = -\rho(\nabla \cdot \mathbf{u})\mathbf{u} - \nabla p + \nu \nabla^2 \mathbf{u} + \mathbf{F}$$

Fluid momentum

Convective force

Pressure force

Viscous force

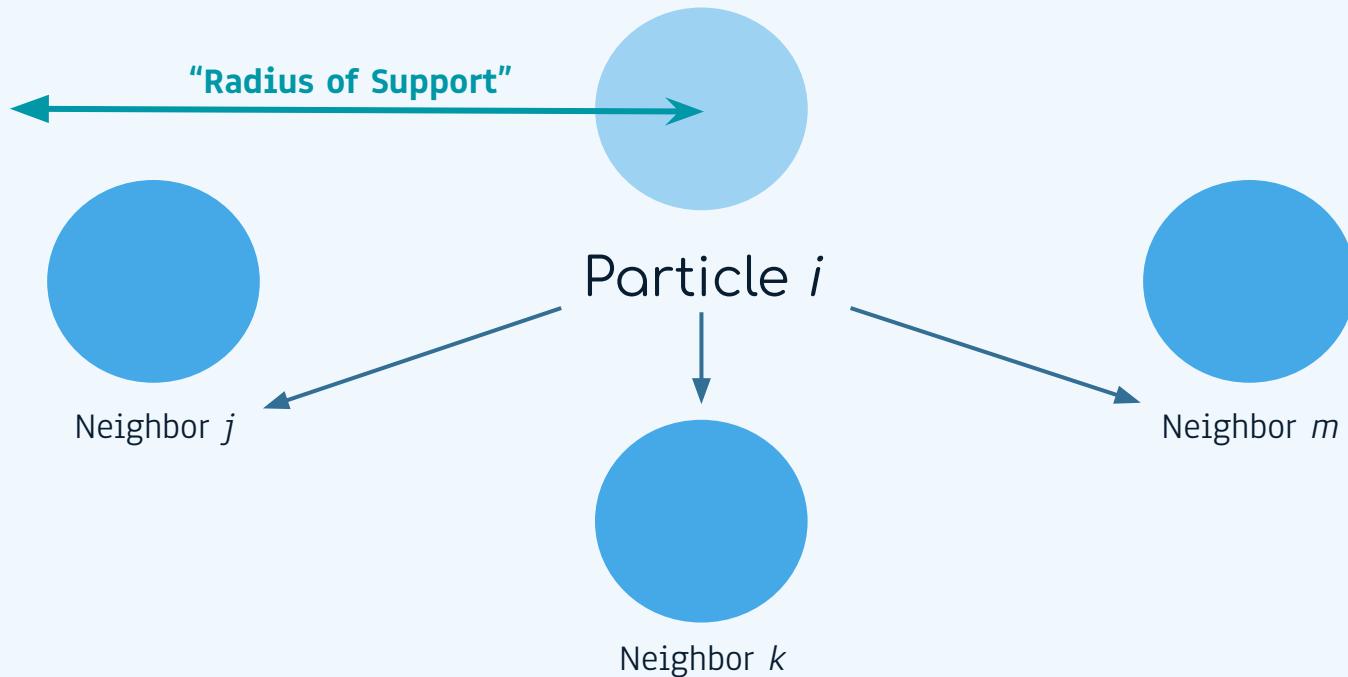
External forces

$$\nabla \cdot \mathbf{u} = 0$$

Incompressibility constraint

Implementation

Particles & Neighbors



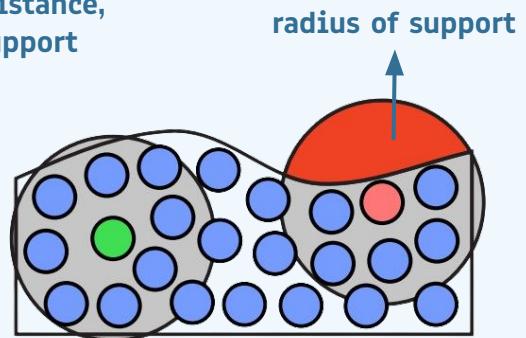
Density Calculation

- Approximate density using masses and kernel function W
 - Applies smoothing and defines influence of neighbors based on distance to i

$$\rho_i = \sum_j m_j \cdot W(|\mathbf{r}_{ij}|, h)$$

ρ : density, \mathbf{r} : relative distance,
 m : mass, h : radius of support

- Iterate over each particle i and each of its neighbors j
 - Sum weighted distance from i to j
 - Add particles within i 's “radius of support” to its neighbor list and store weighted distances



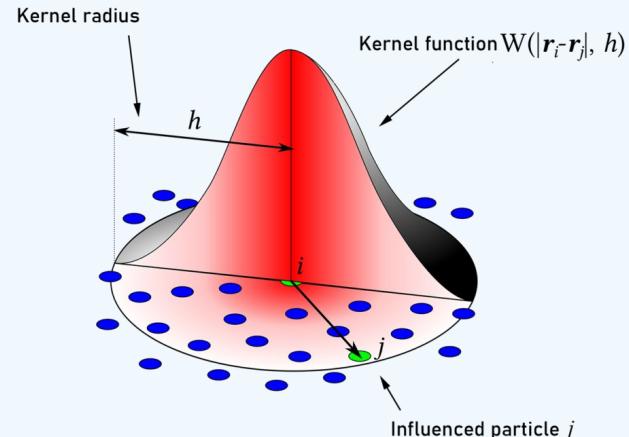
[2] Koschier, D., et al. (2019)

Pressure Calculation

- Determined based on difference between current density and rest density scaled by a fluid pressure constant k and weighted distance

$$P_i = k \sum_j (W(|\mathbf{r}_{ij}|, h) \cdot ((\rho_i - \rho_{\text{rest}}) + (\rho_j - \rho_{\text{rest}})))$$

- Iterate over each particle i
 - Compute pressure difference
 - For each neighbor j
 - Scale pressures by weighted distance
 - Sum pressure force between i and each of its neighbors to find the total pressure force at i



[4] Wikipedia

Viscosity Calculation

- Fluid resistance to flow and deformation
- Apply approximated viscosity impulse based on:
 - Difference in velocity between a particle and its neighbors
 - Weighted distance

$$I = \sum_j \frac{m_j}{\rho_j} \cdot \sigma (\mathbf{v}_j - \mathbf{v}_i) \cdot \beta W(|\mathbf{r}_{ij}|, h)$$

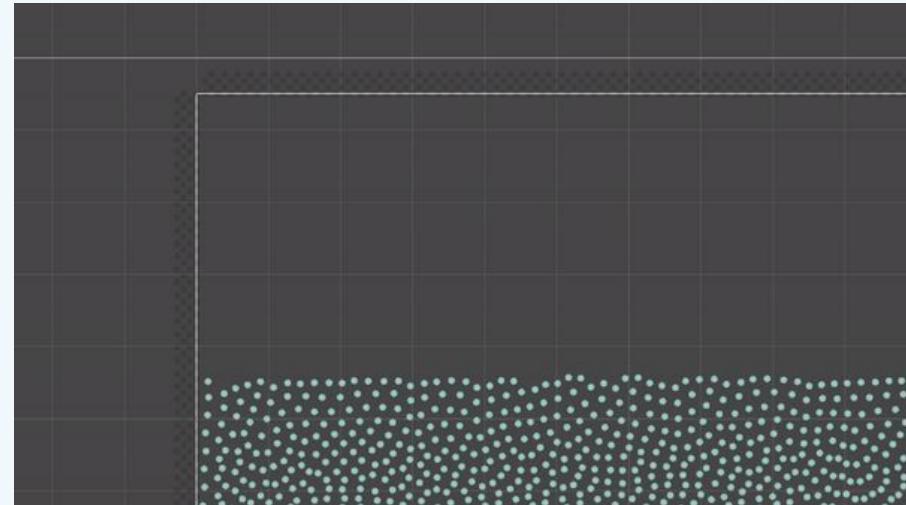
- Constants σ and β allow users to tune the viscosity behavior
 - where $(0 \leq \sigma < 1)$ and $(0 \leq \beta < 1)$
- Approximates:

$$I = \sum_j \frac{m_j}{\rho_j} \cdot (\mathbf{v}_j - \mathbf{v}_i) \cdot \nabla^2 W(|\mathbf{r}_{ij}|, h)$$



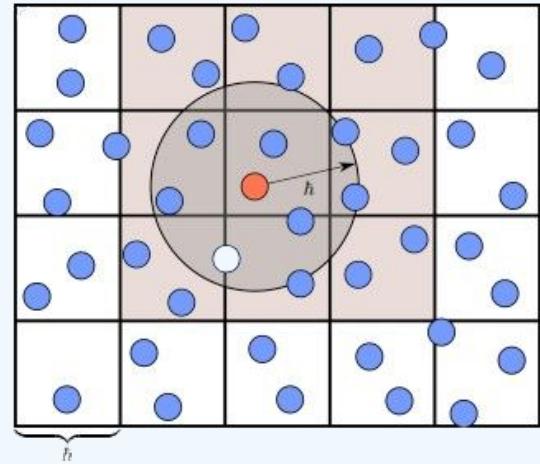
Boundary Conditions

- “Ghost” Particles
 - Multiple layers of fixed particles at the boundary
 - First line of defence
- Fall-back Constraint
 - After updating particle positions, check if any are past the boundary
 - Reposition particles within boundary



Spatial Partitioning

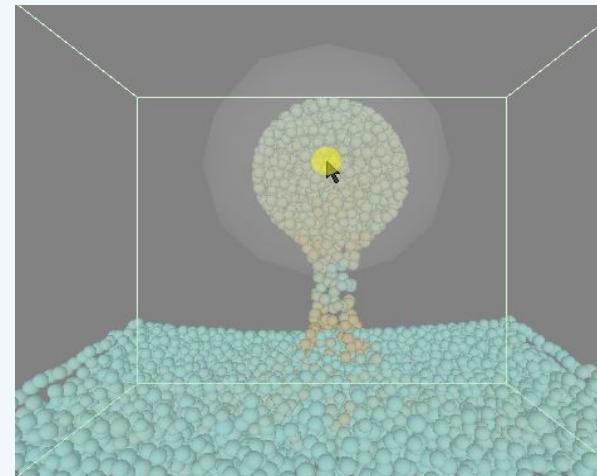
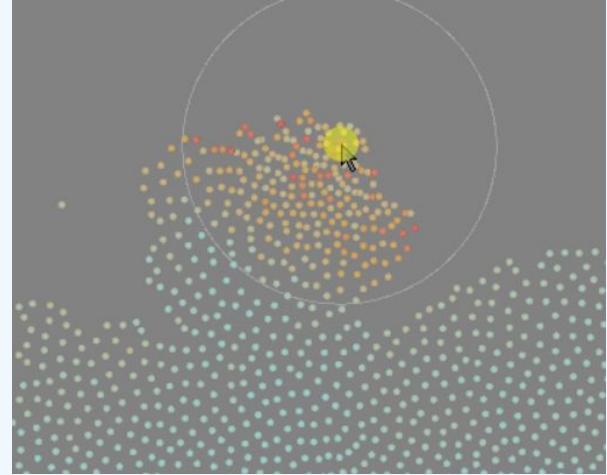
- Divides the space into square (or cube) containers of side length equal to the “radius of support”
- Significantly improves performance by reducing the number of computations needed to find neighbors
- Uses a dictionary with keys based on particle positions in order to place them in respective containers



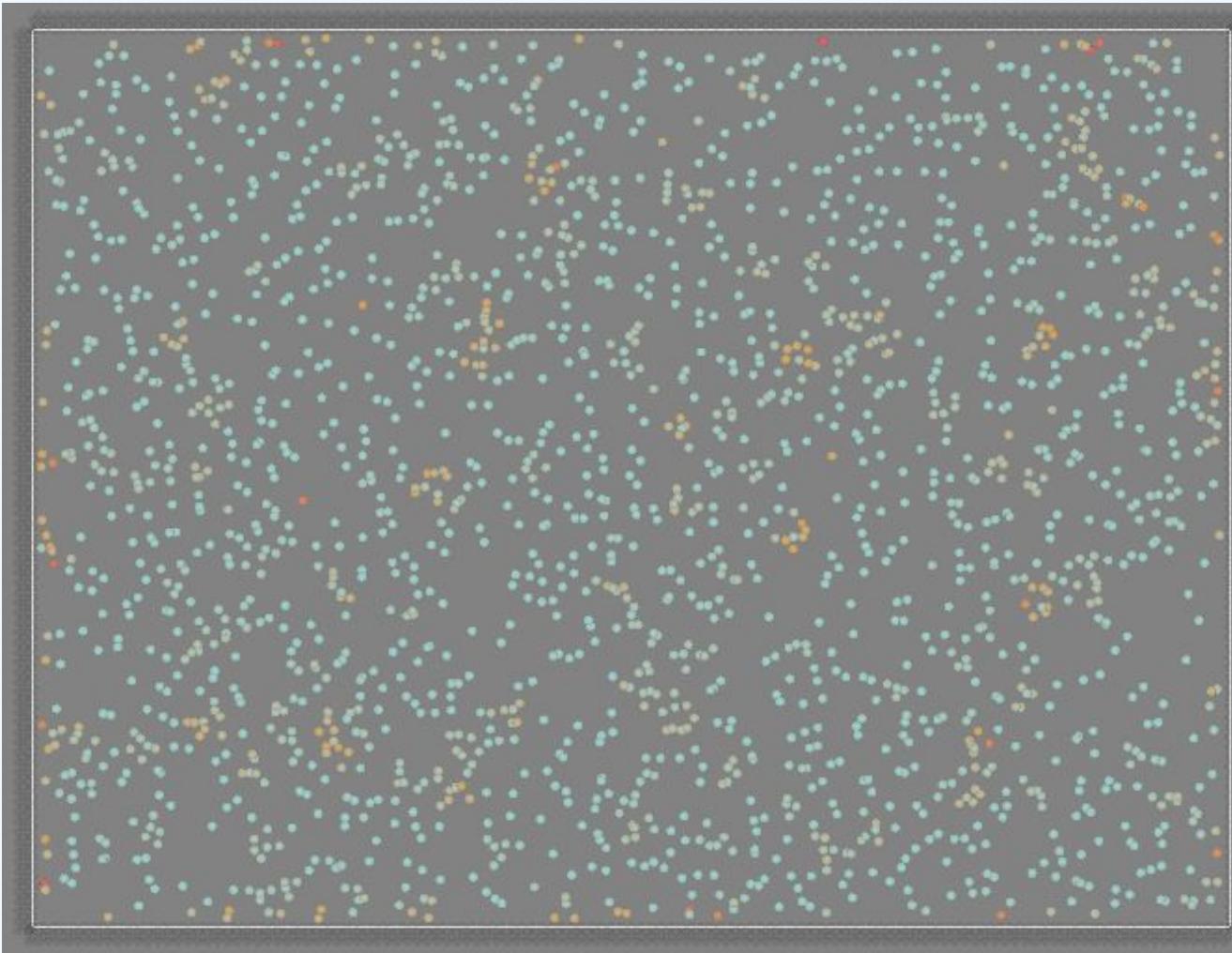
[2] Koschier, D., et al. (2019)

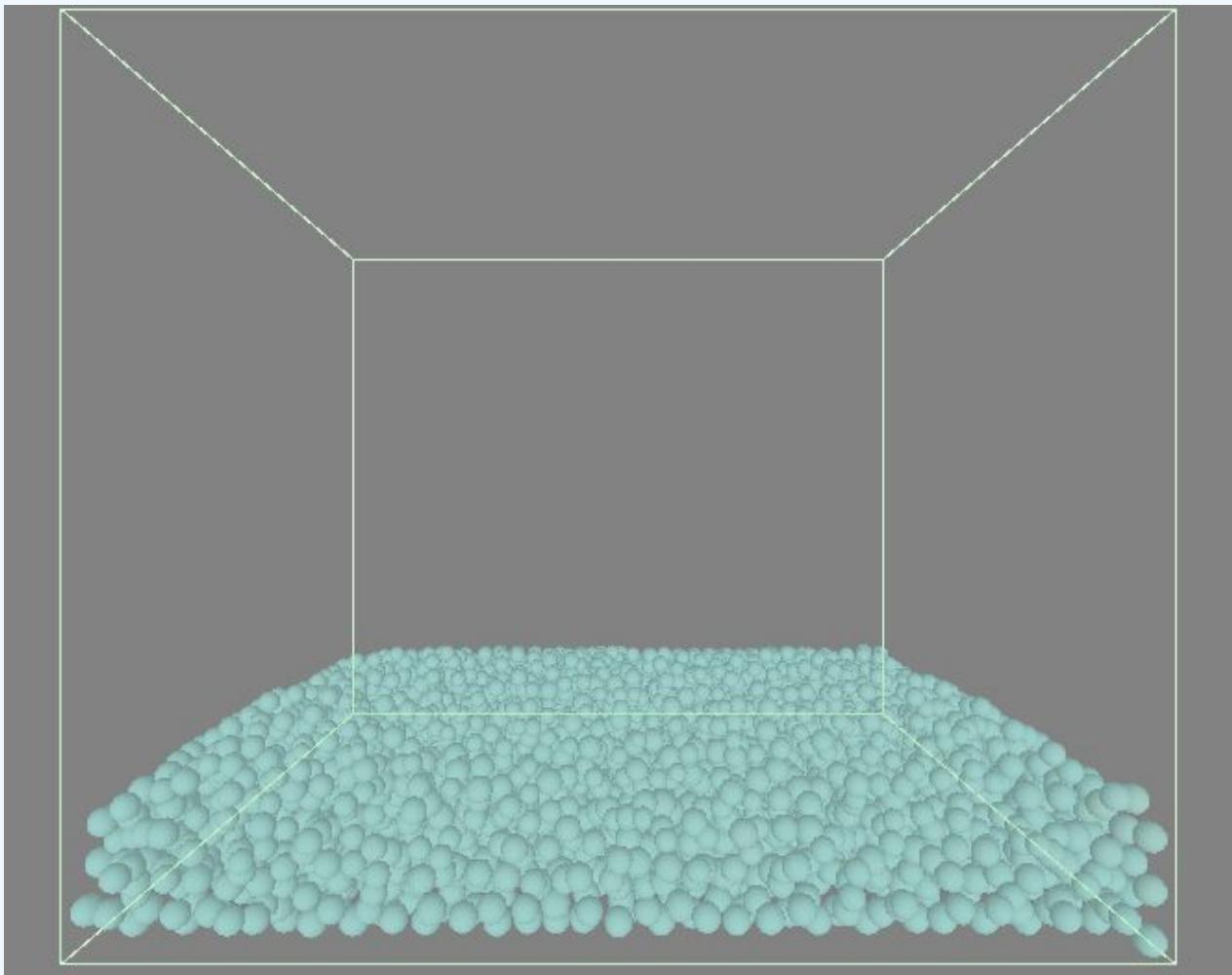
Mouse Interaction

- Clicking creates an attractive force about a radius which allows for fluid manipulation in real-time
- In 3D, a raycast is used to determine the position of the force within the boundary



Results Demo





References

- [1] Pelfrey, B. (2009). Real-Time Physics 103: Fluid Simulation in Games.
- [2] Koschier, D., et al. (2019). Smoothed Particle Hydrodynamics Techniques for the Physics Based Simulation of Fluids and Solids. Eurographics.
- [3] Lauge, S. "Coding Adventure: Simulating Fluids." YouTube, uploaded by Sebastian Lauge, 8 October 2023. <https://www.youtube.com/watch?v=rSKMYc1CQHE>
- [4] "Smoothed-particle Hydrodynamics"
https://en.wikipedia.org/wiki/Smoothed-particle_hydrodynamics